### Detecting Gravitational Waves with Pulsar Timing Arrays Delphine Perrodin

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# Outline

- Introduction to Gravitational Wave detectors
- Introduction to Pulsar Timing Arrays
- Stochastic GW background
- Effect of GW on pulsar signal
- Optimal statistic: Hellings & Downs curve
- Detection techniques

# GW: ripples in curvature of space-time that propagate throughout the universe



# GW detection with ground-based laser interferometers (LIGO, Virgo, GEO)

Photo Courtesy of Virgo

Adapted from NASA figure

### GW detection with pulsars detector arm = Earth to pulsar



Pulsar 2 🚽



Adapted from NASA figure

# Pulsar Timing Array ~ 30 pulsars



David Champion

### **Gravitational Wave Detectors**





eLISA

PTA

#### LIGO/VIRGO



#### PTAs: complementary to LIGO and eLISA



PTAs: frequencies in nanohertz regime

Corresponds to timelines of ~1-30 years

# The International Pulsar Timing Array (IPTA) collaboration:



Image source, clockwse from upper left: http://www.gb.nrao.edu/; http://www.astron.nl/; http://wwww.astron.nl/; http://www.astron.nl/; http://www.astron.nl/; ht

# **Detecting GW using PTAs**

- GW perturb space-time between Earth and pulsars
- MSPs act as "cosmic clocks" thanks to their extraordinarily precise rotation period
- Pulsar timing: precise measurement of pulsar properties: position, rotation period, period derivative, proper motion, parallax, orbital parameters + GW signal?
- Pulsar timing array: use many pulsars; one is not enough to discriminate GW signal

Achieve GW detection using 20 pulsars at ~ 100 ns for 5 years (Jenet et al. 2006)

### Need to increase sensitivity of PTA

- Better telescopes, receivers, backends, software
- Observe over long time span (5-30 years)
- Increase number of observations (higher cadence)
- Increase number of MSPs (pulsar searches)
- Use MSPs with good TOA precision ~ 100 ns
- Use MSPs with low red noise
- Good noise characterization



#### John Rowe Animation/ATNF, CSIRO

### GW signature in Pulsar Timing Residuals Single continuous GW source

Proposed surpermassive black hole binary system: 3C66B. Emitted GW should generate detectable fluctuations in pulsar signals.

Ruled out thanks to pulsar timing observations of B1855+09.





Simulated residuals due to 3c66b

Data from Kaspi, Taylor, Ryba 1994

Jenet et al, 2004

#### Stochastic GW background

- A stochastic GW background is a random GW signal that must be characterized statistically. It is produced by the superposition of many independent, weak, unresolved GW signals, and is therefore most likely Gaussian-distributed.
- It can be cosmological or astrophysical.
- Cosmological: GW left over from the very early universe (inflation period); cosmic strings
- Astrophysical: Supermassive black hole binary background (SMBHB)
- Cosmological background expected to be isotropic; astrophysical background could be isotropic or anisotropic.

#### Stochastic GW background

GW background defined by characteristic strain:

$$h_c(f) = A\left(\frac{f}{\mathrm{yr}^{-1}}\right)^{\alpha}$$

where f is GW frequency, A amplitude, and alpha the spectral index In the case of SMBHB background, alpha = -2/3

Red spectrum: excess power at low frequencies. Overcome low amplitude by observing for long periods of time. However beware of red timing noise!

#### GW signature in pulsar timing residuals

Idea of using pulsars to detect low-frequency GW first developed by Sazhin (1978) and Detweiler (1979): They computed expected induced residuals from GW

Followed by work of Hellings & Downs (1983)
Studying spatial correlations of the timing signals of a group of pulsars at different sky locations
Correlation is calculated in terms of angles between pulsar pairs
Cross-correlation also called "overlap reduction function"

### Optimal statistic: Hellings & Downs curve Overlap reduction function



Courtesy of R. Jenet and G. Hobbs. Original picture from Hellings & Downs (1983)

### **GW detection techniques**

- GW detection pipelines use the "optimal statistic" (HD curve) to search for GW
- Various methods in IPTA used for estimating pulsar parameters; modeling timing noise; search pipelines
- Frequentist and Bayesian methods are both used; sometimes as a combination
- Maximum likelihood function: used in both frequentist and bayesian techniques.
- in bayesian statistics: update prior probabilities in order to obtain posterior probabilities
- in frequentist approach: parameters are found by maximizing the likelihood
- While the goal of search pipelines is to detect GW, non-detections are still useful by placing upper limits on a stochastic background

## Conclusion

- PTAs are well-placed to detect nanohertz-frequency GW in the next 5-10 years
- A combination of frequentist and bayesian (but mostly bayesian!) search techniques are used
- Can improve our "detector" by finding new MSPs, increasing observation cadence and time span, upgrading our instruments and software
- Need to accurately model timing noise